

ECET 211 DC Shunt Motor Demonstration  
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 Room KT 250

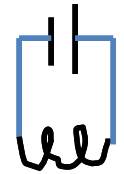
Student Helpers:

- Cullan S. Magnuson and Jason Ringer – move the demo equipment
- Frank Hoffmann – help with measurement
- Emily Bendix – Lab data/notes taken by Emily Bendix

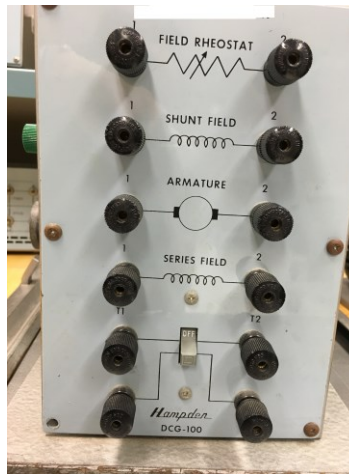
DC MOTOR DEMONSTRATION

- 1/3 HP Motor, 1725 rpm
- 115V DC, 3.4 Amps
- Shunt Field Amp = 0.4 Amps
  - o Rshunt = 254.3 Ohms (measured with DMM)
- $I_{SH} = \frac{115 V}{254.3 \Omega} = 0.45 A$  (calculation)

ISH calculation



254.3 Ω



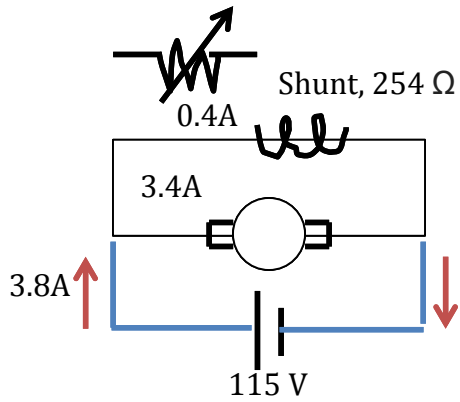
$R_A = 5.4 \Omega$  (armature resistance measurement)

Rotations (rotate the shaft 5 steps from 0°, 60°, 120°, 180°, ..):

#2	#3	#4	#5	Average
5.3 Ω	5.3 Ω	5.3 Ω	5.4 Ω	5.35 Ω

$$(R_{Ave} = \frac{R_{A1} + R_{A2} + R_{A3} \dots}{n} = 5.4 \Omega)$$

- Rheostat = 85Ω (adjusts, controls the amount of current provided to the shunt)
- Allow us to reduce the Ish from the rated 0.4A to  $I_{sh} = 115V / (254.3 + 85) = 115V / 339.3\Omega = 0.34 A$ , to weaken the flux for extra speed control
- $I_{SH}$  reduced ( $\Phi$ , flux, reduced as well)



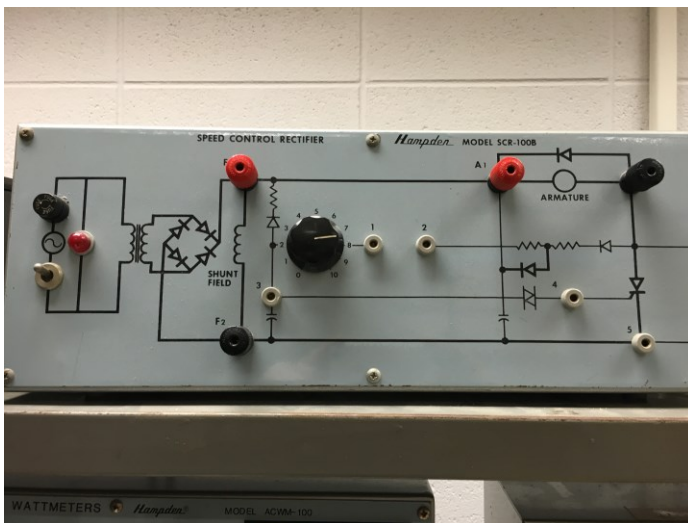
Power Supply

AC 120V

10A (estimated max)

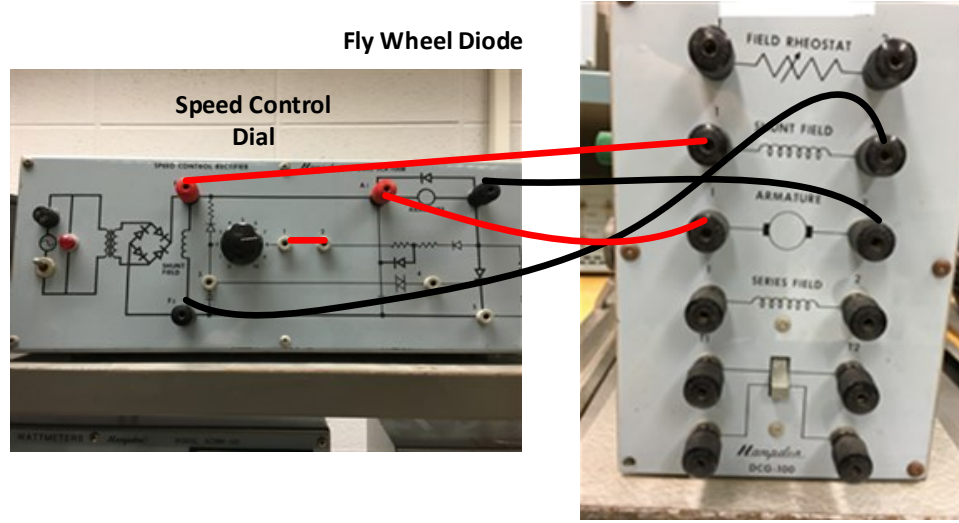
$$I_T = I_{SH} + I_A = 3.4 + 0.4 = 3.8A$$

### DC Motor Speed Controller (SCR-based)



Adjust dial 0,1,2,..9	100% Full-wave	75% Full-wave (triggered at)	50% Full-wave (triggered at)	25% Full-wave (triggered at)
Motor Speed	100% of rated motor speed	75% of rated motor speed	50% of rated motor speed	25% of rated motor speed

## Wiring Diagram for DC Shunt Motor Speed Control



AC  
Vrms = 120V  
60Hz

$$e(t) = -L \frac{\Delta i}{\Delta t} \quad (L = \text{inductance})$$

Full-wave bridge rectifier  
(pulsating DC),  $V_p = 169.7$

$$e(t) = -L \frac{I_{max} - I_{min}}{t_2 - t_1} = \frac{3.4 - 0}{t}$$

DC =  $V_p * 0.90$   
DC = 152.73

- Fly wheel diode (short circuit, when power is turned off)
  - o The induced voltage  $e(t)$  across the armature, will force the fly wheel to turn-on, to consume the armature stored energy
  - o Protect SCR from having a high-voltage at its anode
- 120.6V (from Kill A Watt reader)
- when the motor starts, reads 119.8 ~ 119.9V ( $I = 1.59A$ )
- As more load is applied to the motor, the amperage increases:

1.87 A
1.94 A
2.09 A
2.40 A
2.54 A
2.70 A
2.98 A
3.0 A
3.12 A



Increase in load,  
Dial 4, 1700 rpm